

基变换与坐标变换

$$\vec{\alpha} = \begin{pmatrix} 7 \\ 3 \\ 1 \end{pmatrix} = 7\vec{e}_1 + 3\vec{e}_2 + \vec{e}_3 = -\vec{\alpha}_1 - 2\vec{\alpha}_2 + 6\vec{\alpha}_3 \quad (\vec{\alpha}_1, \vec{\alpha}_2, \vec{\alpha}_3) = (\vec{e}_1, \vec{e}_2, \vec{e}_3) \underline{(\vec{\alpha}_1, \vec{\alpha}_2, \vec{\alpha}_3)}$$

1. 基变换: 设线性空间 V 有两组基 $\vec{\alpha}_1, \dots, \vec{\alpha}_n$ 和 $\vec{\beta}_1, \dots, \vec{\beta}_n$,

$$\begin{cases} \vec{\beta}_1 = k_{11}\vec{\alpha}_1 + k_{21}\vec{\alpha}_2 + \dots + k_{n1}\vec{\alpha}_n = (\vec{\alpha}_1 \dots \vec{\alpha}_n) \begin{pmatrix} k_{11} \\ k_{21} \\ \vdots \\ k_{n1} \end{pmatrix} \\ \vec{\beta}_2 = k_{12}\vec{\alpha}_1 + k_{22}\vec{\alpha}_2 + \dots + k_{n2}\vec{\alpha}_n = (\vec{\alpha}_1 \dots \vec{\alpha}_n) \begin{pmatrix} k_{12} \\ k_{22} \\ \vdots \\ k_{n2} \end{pmatrix} \\ \vdots \\ \vec{\beta}_n = k_{1n}\vec{\alpha}_1 + k_{2n}\vec{\alpha}_2 + \dots + k_{nn}\vec{\alpha}_n = (\vec{\alpha}_1 \dots \vec{\alpha}_n) \begin{pmatrix} k_{1n} \\ \vdots \\ k_{nn} \end{pmatrix} \end{cases}$$

$$\Rightarrow (\vec{\beta}_1 \vec{\beta}_2 \dots \vec{\beta}_n) = (\vec{\alpha}_1 \dots \vec{\alpha}_n) \begin{pmatrix} k_{11} & \dots & k_{1n} \\ \vdots & & \vdots \\ k_{n1} & \dots & k_{nn} \end{pmatrix} = \underline{(\vec{\alpha}_1 \dots \vec{\alpha}_n) P}$$

$\Rightarrow P$ 称之为从基 $\vec{\alpha}_1, \dots, \vec{\alpha}_n$ 到 $\vec{\beta}_1, \dots, \vec{\beta}_n$ 的过渡矩阵.

$$\Rightarrow (\vec{\alpha}_1, \dots, \vec{\alpha}_n) = (\vec{\beta}_1, \dots, \vec{\beta}_n) P^{-1}$$

2. 坐标变换:

$$\begin{aligned} \vec{\alpha} &= a_1\vec{\alpha}_1 + \dots + a_n\vec{\alpha}_n = \underline{(\vec{\alpha}_1 \dots \vec{\alpha}_n)} \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} = \underline{(\vec{\beta}_1, \dots, \vec{\beta}_n) P^{-1}} \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \\ &= b_1\vec{\beta}_1 + \dots + b_n\vec{\beta}_n = \underline{(\vec{\beta}_1 \dots \vec{\beta}_n)} \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = \underline{(\vec{\alpha}_1, \dots, \vec{\alpha}_n) P} \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} \end{aligned}$$

$$\therefore (\vec{\beta}_1, \dots, \vec{\beta}_n) = (\vec{\alpha}_1, \dots, \vec{\alpha}_n) P \Rightarrow$$

$$\Rightarrow \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} = P \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}, \quad \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = P^{-1} \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}$$

例1. 在 $P_3(x)$ 中取两个基

$$\vec{\alpha}_1 = x^3 + 2x^2 - x, \quad \vec{\alpha}_2 = x^3 - x^2 + x + 1, \quad \vec{\alpha}_3 = -x^3 + 2x^2 + x + 1, \quad \vec{\alpha}_4 = -x^3 - x^2 + 1$$

$$\vec{\beta}_1 = 2x^3 + x^2 + 1, \quad \vec{\beta}_2 = x^2 + 2x + 2, \quad \vec{\beta}_3 = -2x^3 + x^2 + x + 2, \quad \vec{\beta}_4 = x^3 + 3x^2 + x + 2$$

求坐标变换公式.

解: $(\vec{\alpha}_1, \vec{\alpha}_2, \vec{\alpha}_3, \vec{\alpha}_4) = (x^3, x^2, x, 1) \begin{pmatrix} 1 & 1 & -1 & -1 \\ 2 & -1 & 2 & -1 \\ -1 & 1 & 1 & 0 \\ 0 & 1 & -1 & 1 \end{pmatrix} = (x^3, x^2, x, 1) A$

$$(\vec{\beta}_1, \vec{\beta}_2, \vec{\beta}_3, \vec{\beta}_4) = (x^3, x^2, x, 1) \begin{pmatrix} 2 & 0 & -2 & 1 \\ 1 & 1 & 1 & 3 \\ 0 & 2 & 1 & 1 \\ 1 & 2 & 2 & 2 \end{pmatrix} = \underline{(x^3, x^2, x, 1) B}$$

$$\Rightarrow (x^3, x^2, x, 1) = (\vec{\alpha}_1, \vec{\alpha}_2, \vec{\alpha}_3, \vec{\alpha}_4) A^{-1}$$

$$\Rightarrow (\vec{\beta}_1, \vec{\beta}_2, \vec{\beta}_3, \vec{\beta}_4) = (\vec{\alpha}_1, \vec{\alpha}_2, \vec{\alpha}_3, \vec{\alpha}_4) A^{-1} B \quad \Rightarrow P = A^{-1} B$$

$$\Rightarrow \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} = \underline{A^{-1} B} \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}, \quad \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = \underline{B^{-1} A} \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \quad P^{-1} = \underline{B^{-1} A}$$

现在求 $B^{-1}A$. 做法, $(B|A) \sim (E|B^{-1}A), (A|B) \sim (E|A^{-1}B)$

$$B^{-1}A = \begin{pmatrix} 0 & 1 & -1 & 1 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & -1 & 1 & -1 \end{pmatrix}$$